



THE ALTAIR MOTION SOLUTION

Rajiv Rampalli • Sr. VP Software Development • Feb. 13, 2019



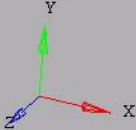
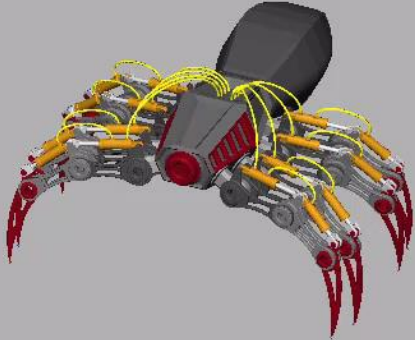
WHAT WE WILL DISCUSS TODAY...



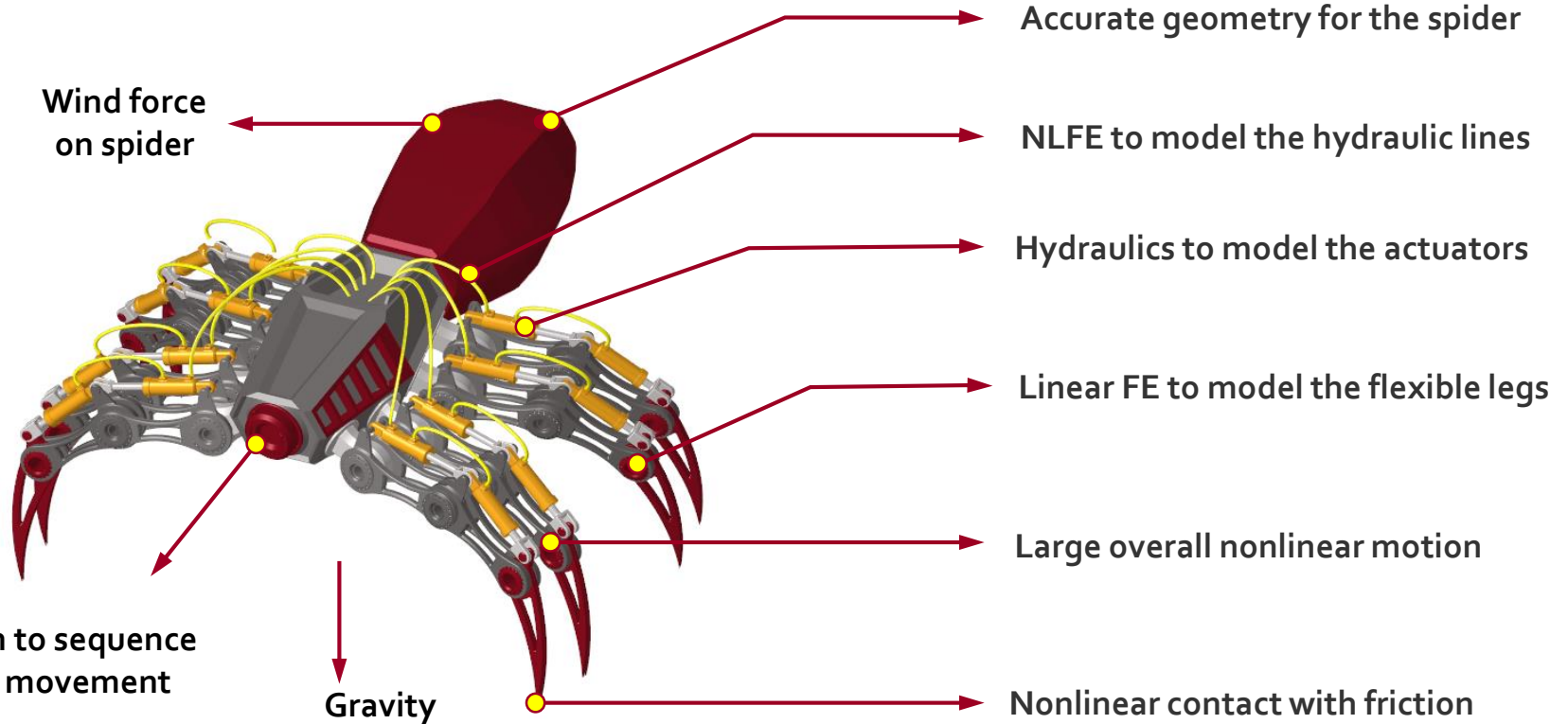
THE CURRENT SOLUTION



1: MS Model
Transient : Time = 0.000000 : Frame 1



SYSTEM SIMULATION OF A SPIDER



THE ALTAIR MOTION SOLUTION

1: ASSEMBLE



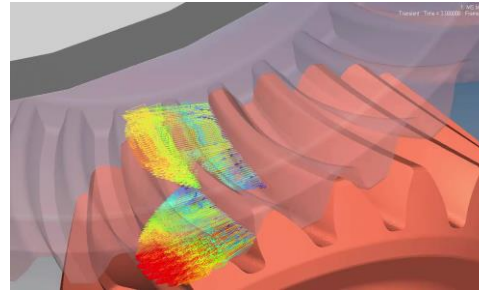
Model Building

2: SOLVE



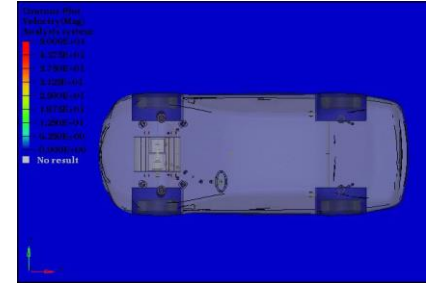
Numerical Solution

3: EVALUATE



Post-Processing

4: IMPROVE



Optimization & DOE

HyperWorks → MotionSolve

SolidThinking → Inspire Motion



#1: QUICKLY ANALYZE THE MOTION OF CAD ASSEMBLIES

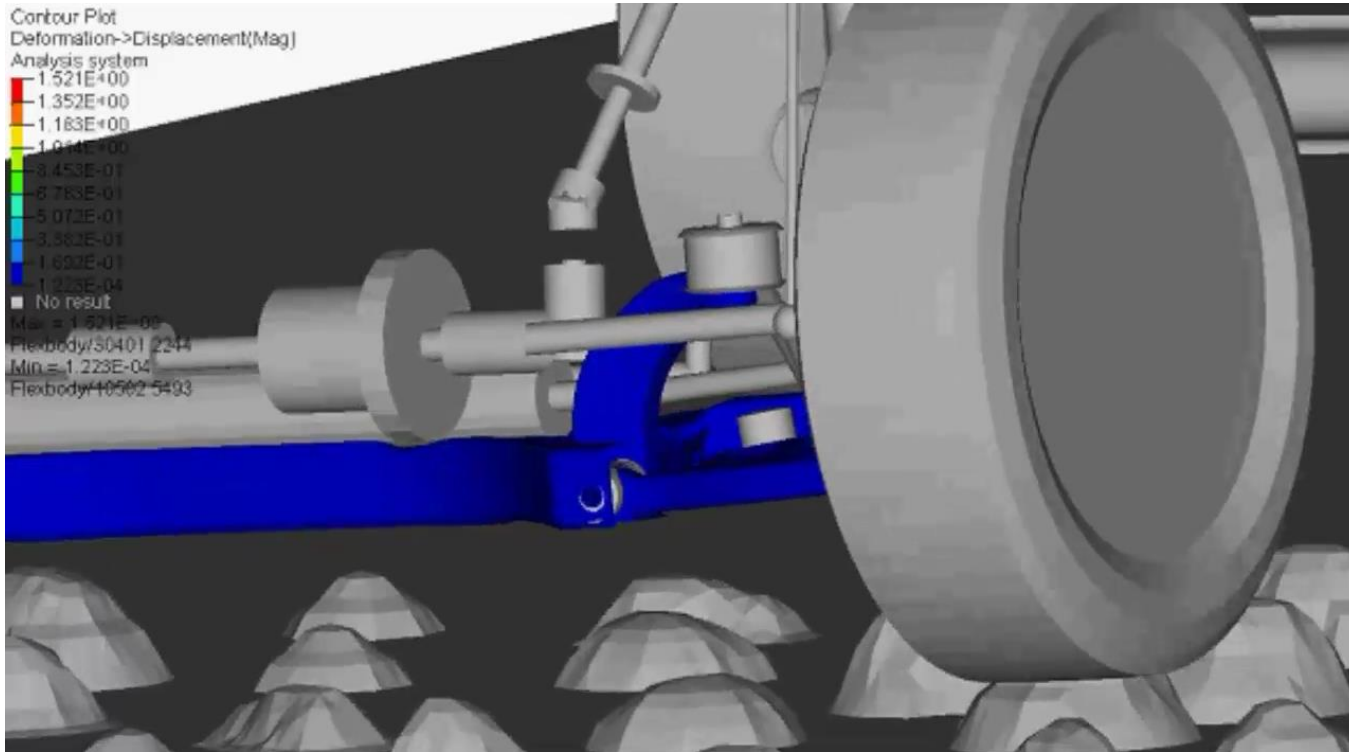


Kinematics:

- Study relative motion between parts
- Compute forces required to achieve a required motion
- Determine design to achieve the required motion



#2: CHARACTERIZE SYSTEM BEHAVIOR DURING NORMAL OPERATION

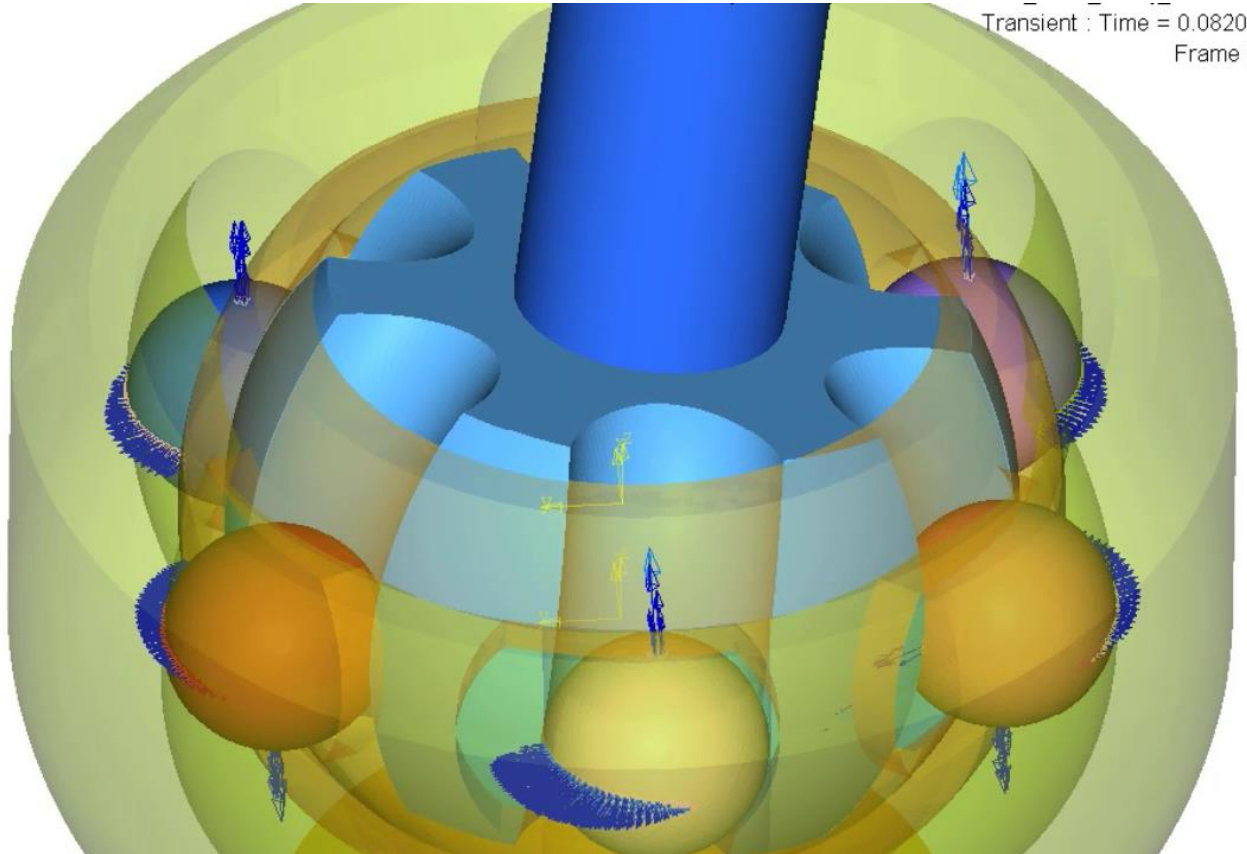


Dynamics:

- Determine nonlinear dynamic response of system
- Include flexible bodies in your model
- Compute stress, strain & deformation
- Perform subsequent fatigue analysis



#3: UNDERSTAND & IMPROVE CONTACT DOMINATED SYSTEMS

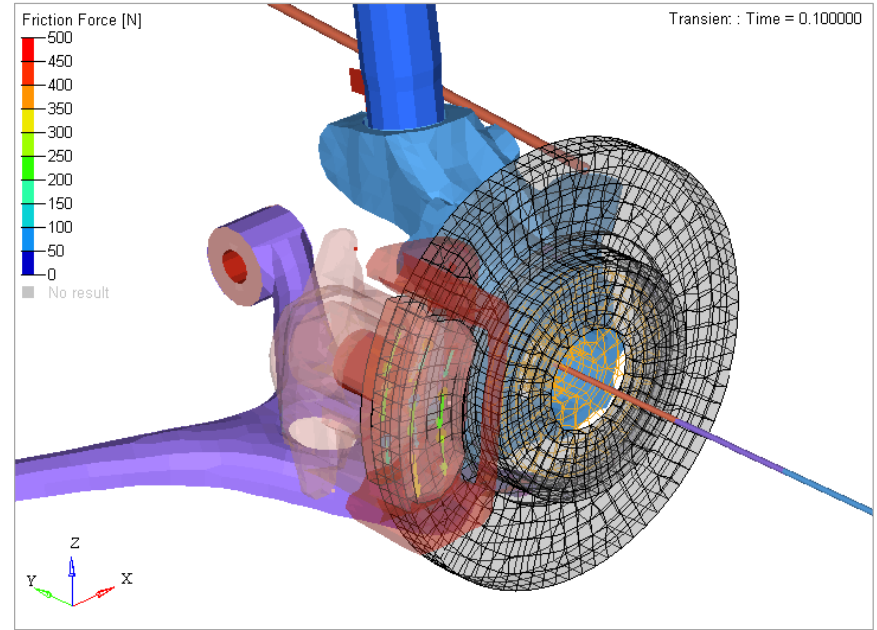
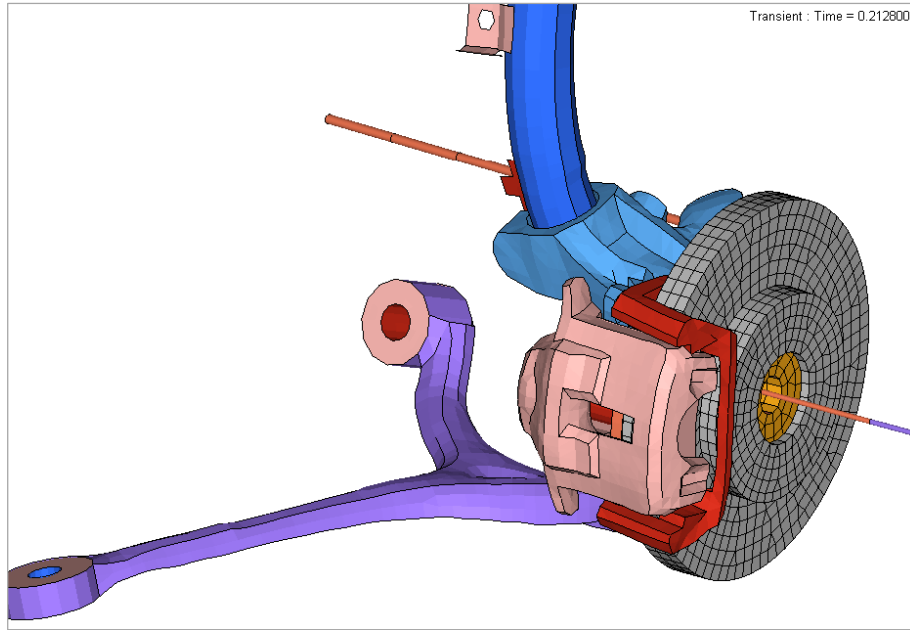


Contact:

- Use the CAD geometry you have
- Specify normal and friction force properties
- Simulate to get accurate behavior
- Examine detailed response to understand behavior



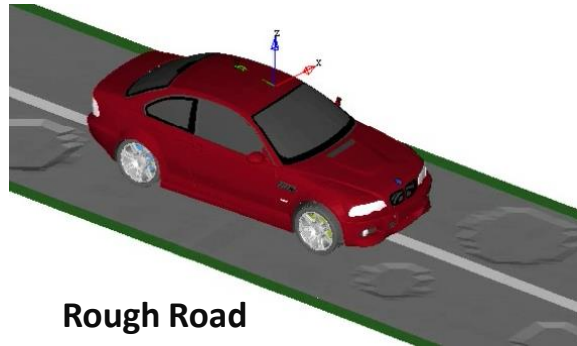
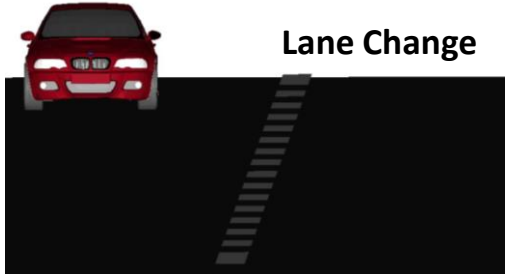
#4: MINIMIZE THE EFFECTS OF VIBRATION



Vibration: Predict & improve system level vibration



#5: CERTIFY DESIGNS



Virtual Validation:

- Advanced driver to simulate complex events
- Tire-terrain interaction to simulate realistic conditions
- Integrated DOE engine for design exploration
- Standardized reports

Certification: Does the design function as intended for all scenarios?



#6: SIMULATE AND IMPROVE COMPLEX SYSTEMS

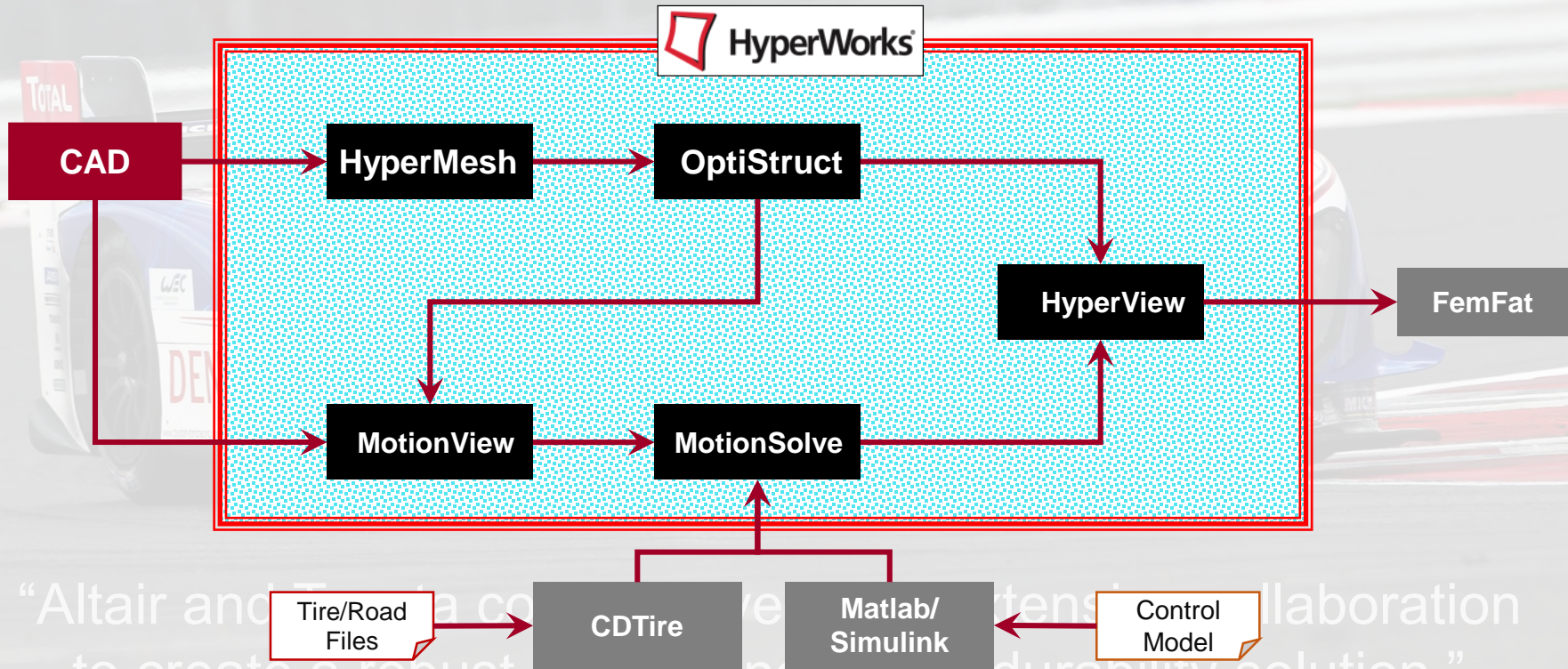


System Model:

- Multibody model
- Actuation model
- Motor model
- Control model



MotionSolve in Toyota, Japan

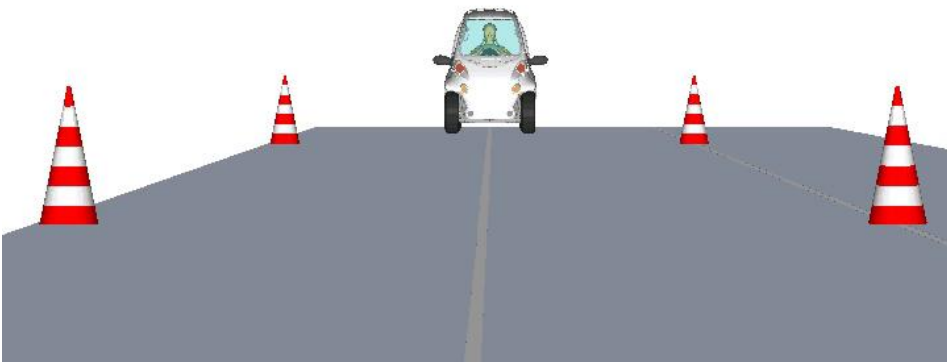


“Altair and Toyota collaborated to create a robust end-to-end virtual durability solution.”

“Smooth Driving To The Town”

車速**30Km**一定 ダブルレーンチェンジ

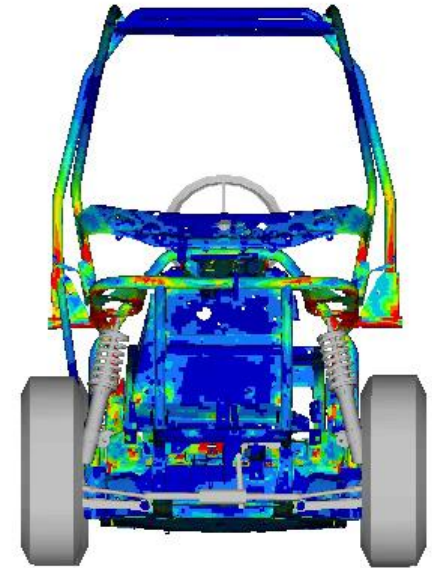
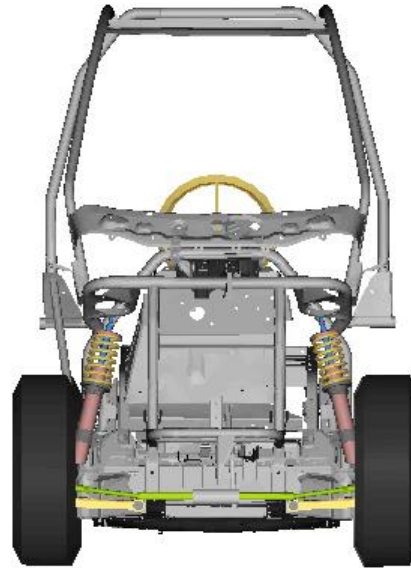
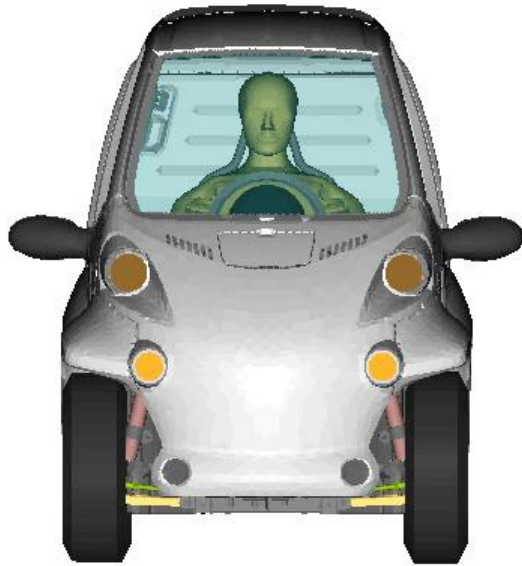
calculation



experiment



TOYOTA AUTO BODY – ELECTRIC CAR DEVELOPMENT



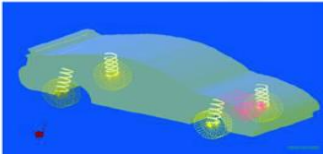
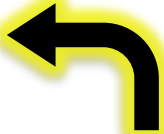
Accurate component loads for fatigue analysis



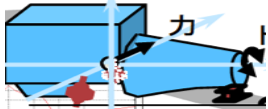


TOYOTA GROUP: PLANNING TEAM

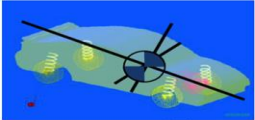
HARDWARE
PROCESS



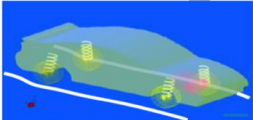
Full Vehicle simulation



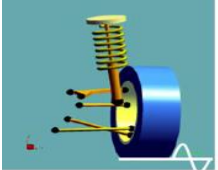
Power train & engine mounts



Vehicle Inertia properties



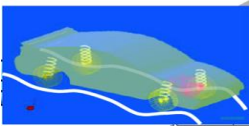
Springs



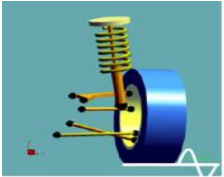
Hard Points



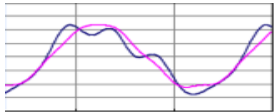
Steering EPS Control



Body transfer force
Bushing Geometry



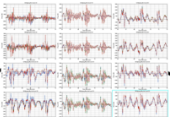
K & C



Shock absorber
Nonlinear Characteristics



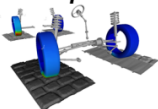
MOTIONSOLVE



Test Data



CAD Data



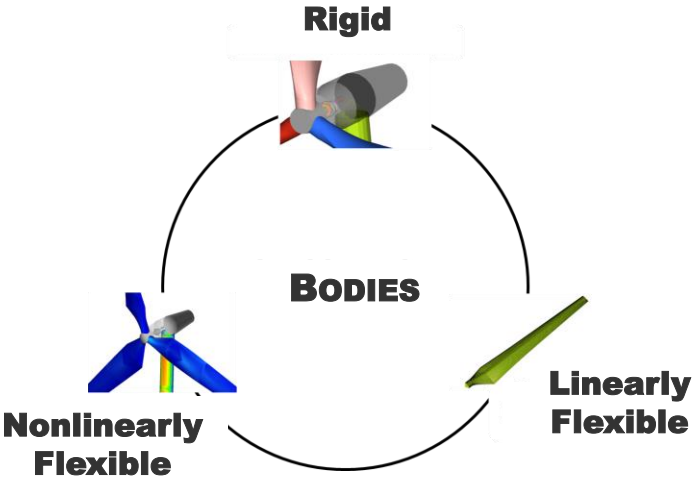
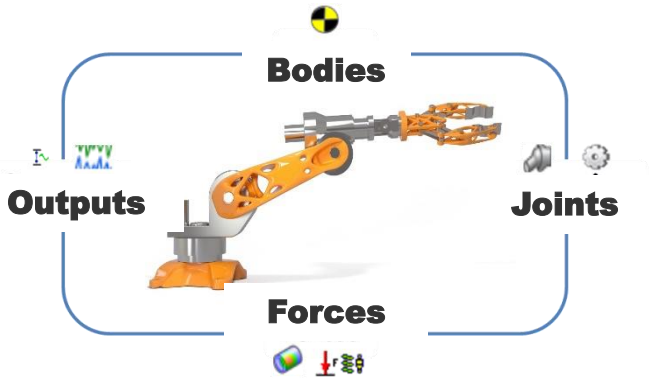
Parametric Models

1. Assemble

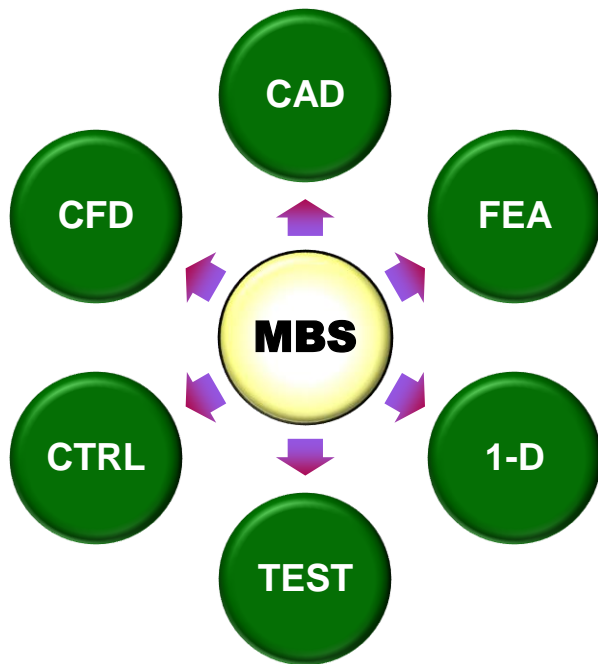
2. Solve

3. Evaluate

4. Improve



MOTIONSOLVE



1. Assemble 2. Solve

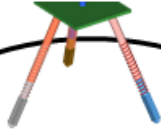
3. Evaluate 4. Improve

- ✧ 2nd Order Differential-Algebraic Equations
- ✧ Sophisticated DAE solvers
- ✧ State of the art linear solvers
- ✧ Thoroughly validated with real models
- ✧ Fast, robust and accurate

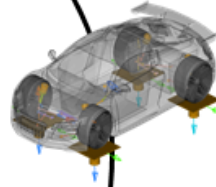


MOTIONSOLVE

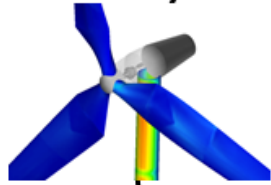
Track & trace component motion



View Animations with force vectors



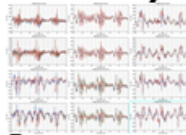
View deformation, stress & strain



Results visualization



Publish CAE reports



Plot, compare, correlate

1. Assemble

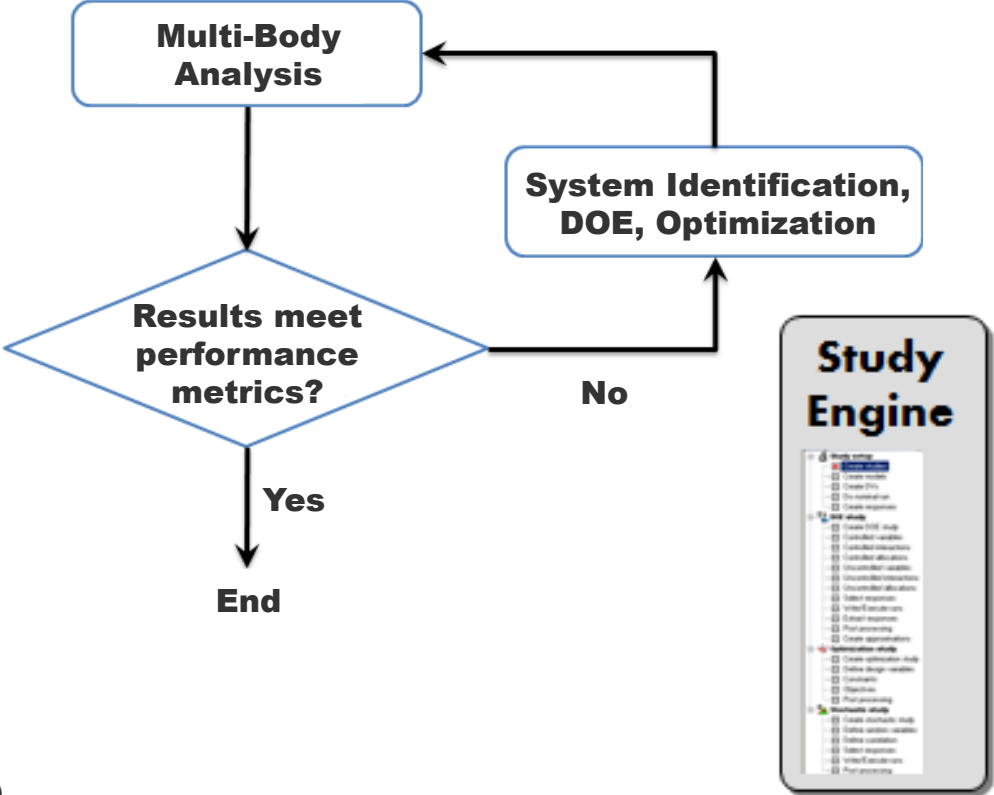
2. Solve

3. Evaluate

4. Improve



MOTIONSOLVE



1. Assemble

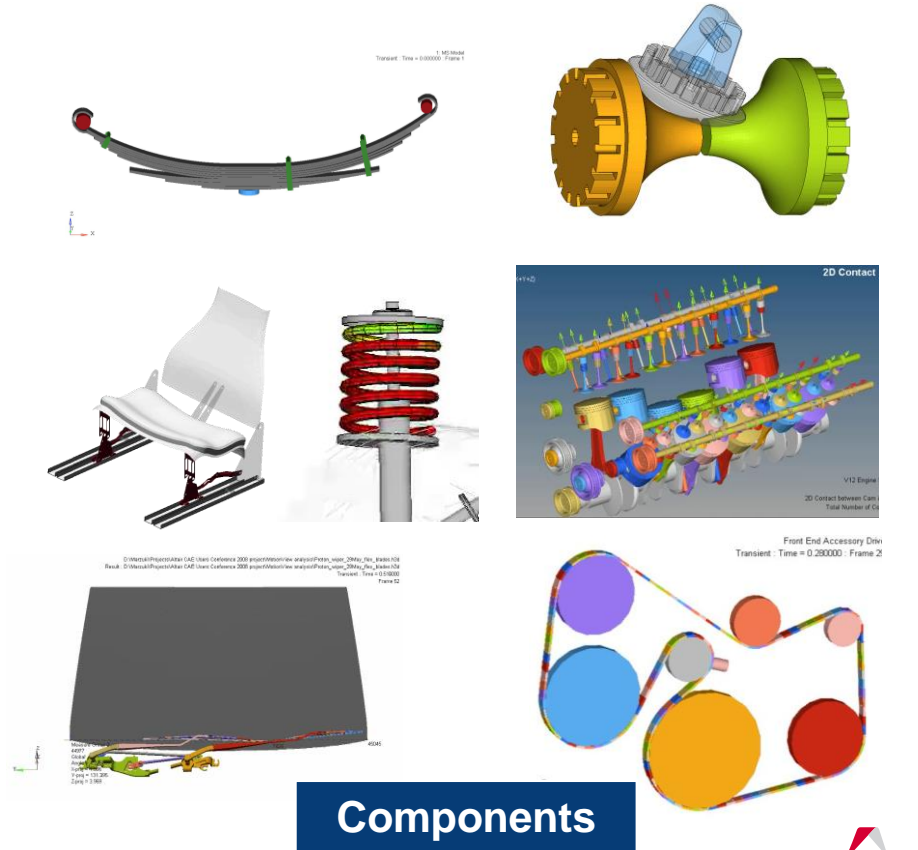
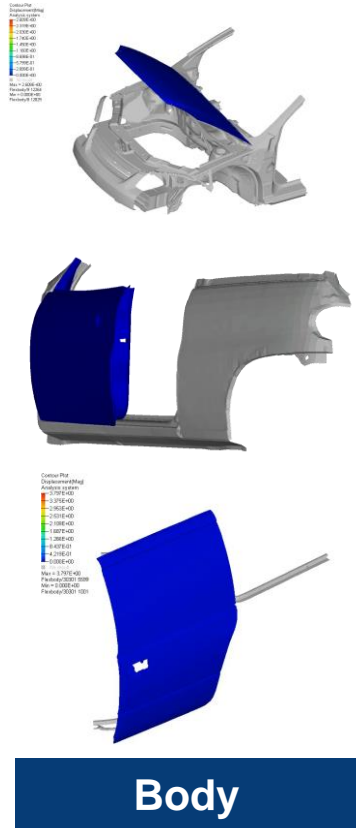
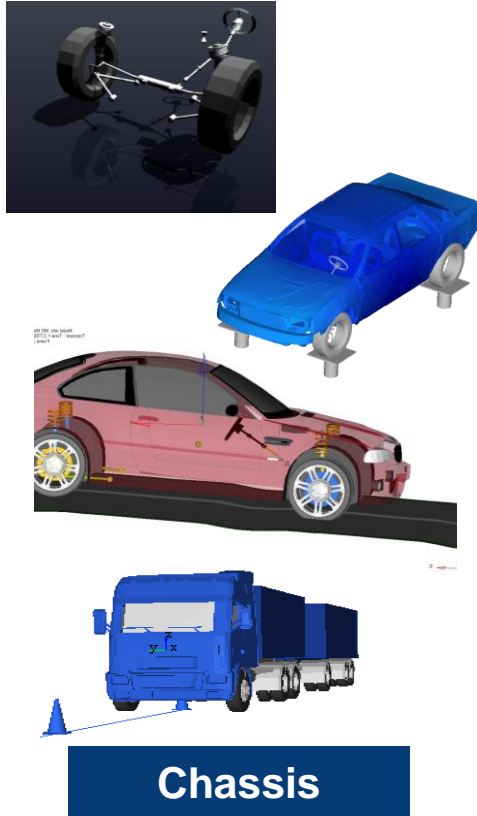
2. Solve

3. Evaluate

4. Improve



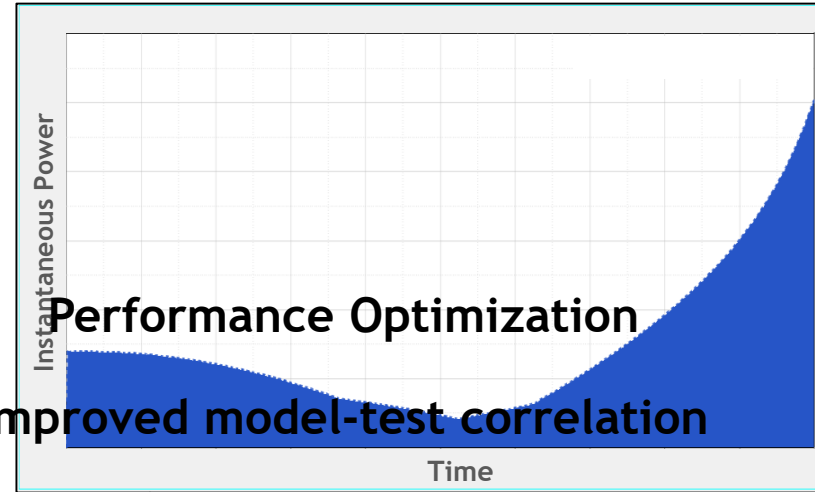
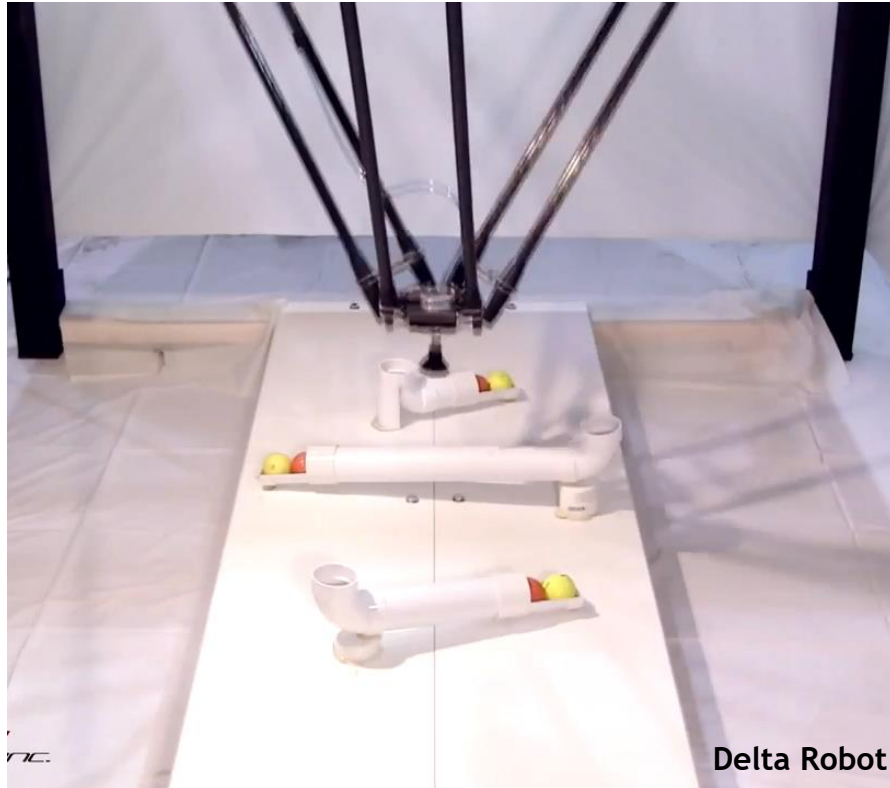
MOTIONSOLVE FOR AUTOMOTIVE



KEY HW 2019.0 ENHANCEMENTS



ANALYTICAL DESIGN SENSITIVITY & OPTIMIZATION



Performance Optimization

Improved model-test correlation

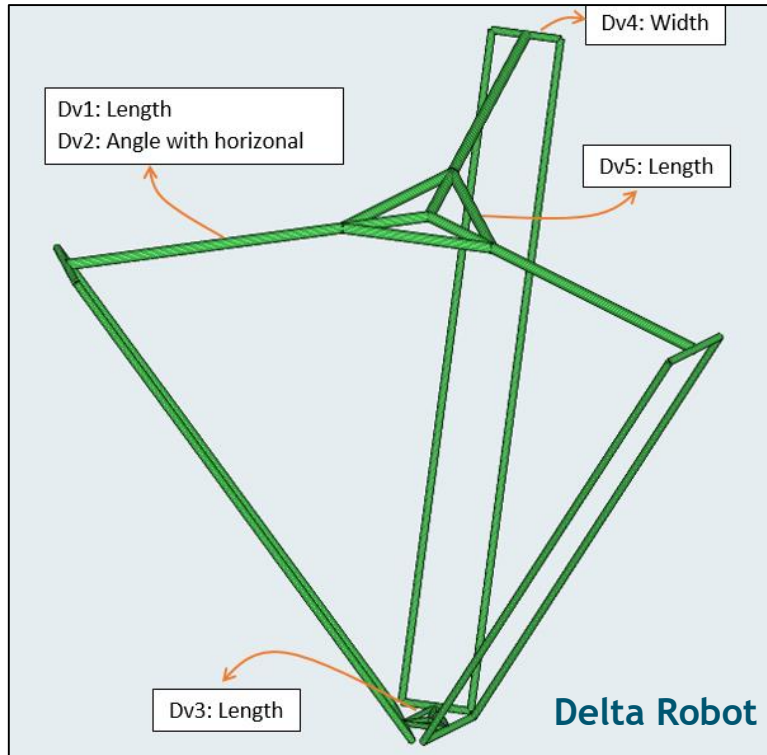
Optimal Control

Given a work cycle, what is the design that minimizes the energy used by the Delta robot?

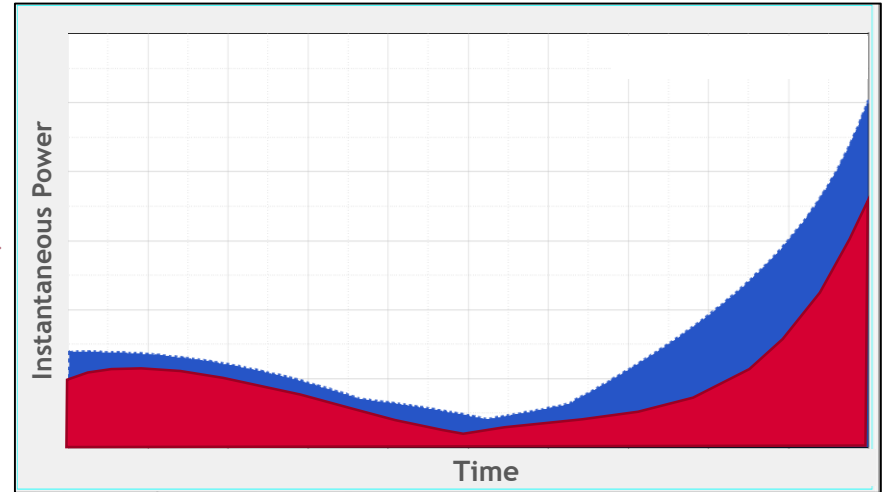
For a specific design & work-cycle, find the motor torques that minimize the total required energy



ANALYTICAL DESIGN SENSITIVITY & OPTIMIZATION



Given a work cycle, what is the design that minimizes the energy used by the Delta robot?

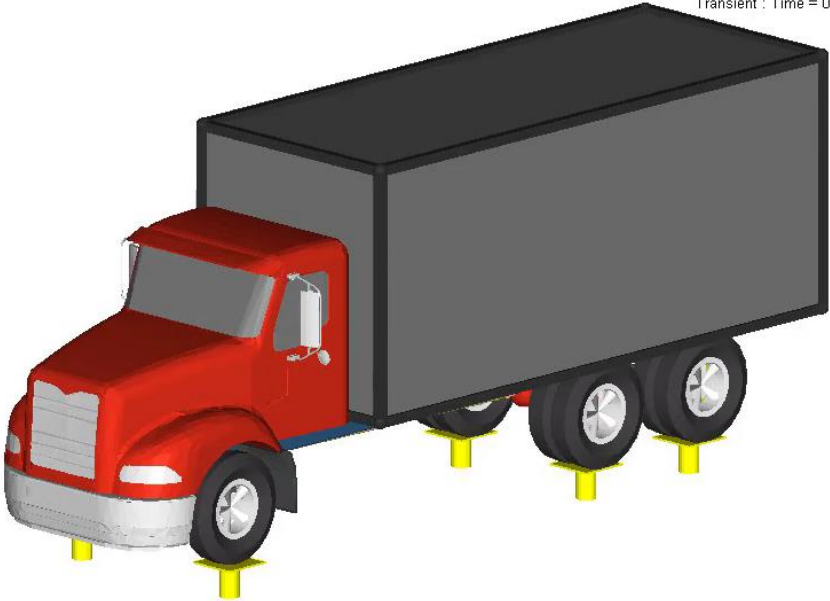


Energy/cycle reduction = 30%
Total CPU Time = 60s

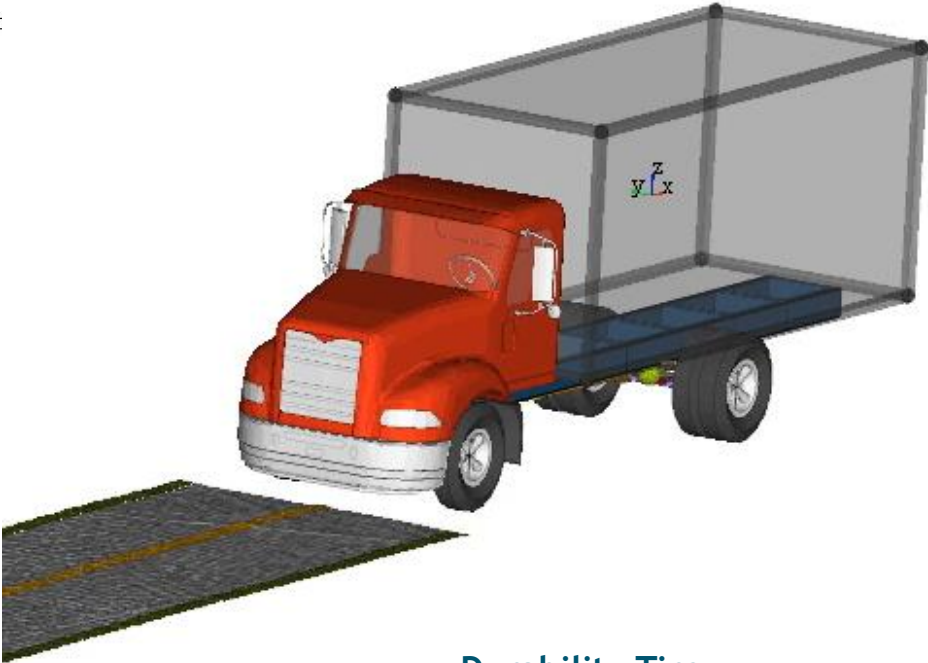


DURABILITY SIMULATIONS

Transient : Time = 0.000000



N-Post test rig



Durability Tire



ROAD COURSE DRIVE EVENT

RoadCourseDrive (ev_rd_course_drive)
✕

Road property file

D:\Altair\2019.0.0.51\hw\mdl\autoentities\properties\Tires\MF_SWIFT\TNO_FlatRoad.rdf

Path profile

Straight line
 Road centerline
 Curve

Velocity profile

Constant
 Curve

Units : Model

Velocity : 10000.0

End time [s] : 10.0

Look ahead time [s] : 0.5

Prediction step size [s] : 0.01

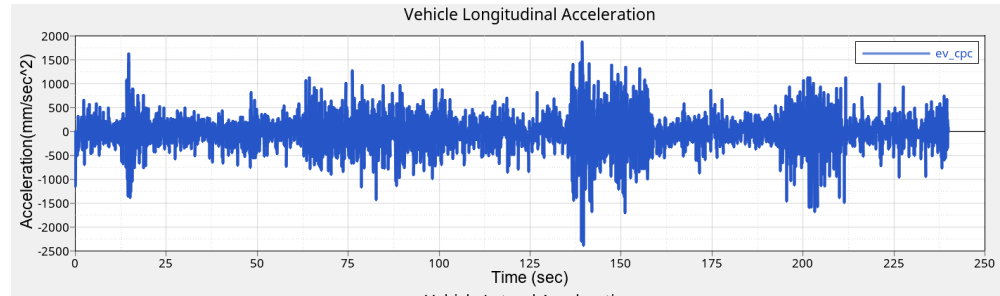
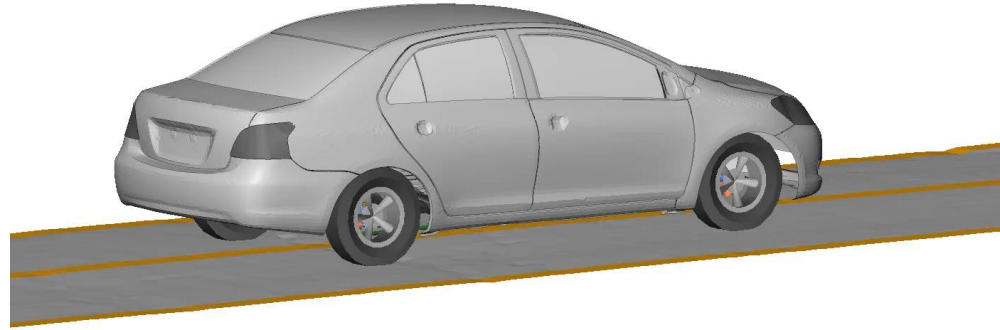
Print interval [s] : 0.05

Show Driver Output Settings Event Specific Solver Settings

Solver Input File

D:\work-1010\TEST\19build51\events\ev_rd_course_drive.xml

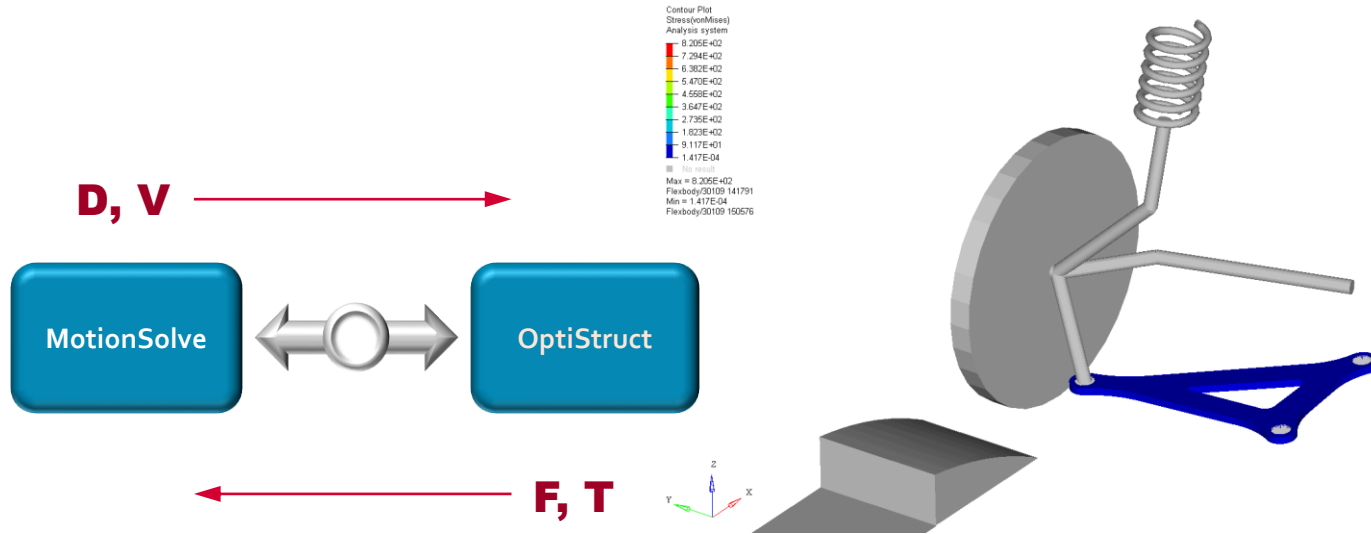
Simulation Settings
Output Options
Run
Apply
Cancel



WHAT'S IN DEVELOPMENT NOW



NONLINEAR FINITE ELEMENTS VIA COSIMULATION



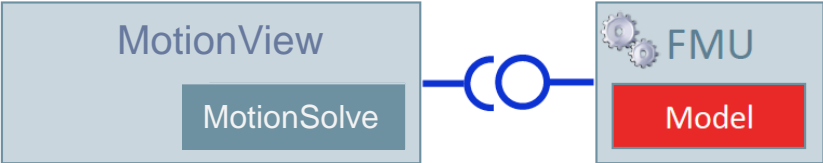
Why:

- Reuse FE models
- Plastic deformation
- Nonlinear materials
- Flex body contact

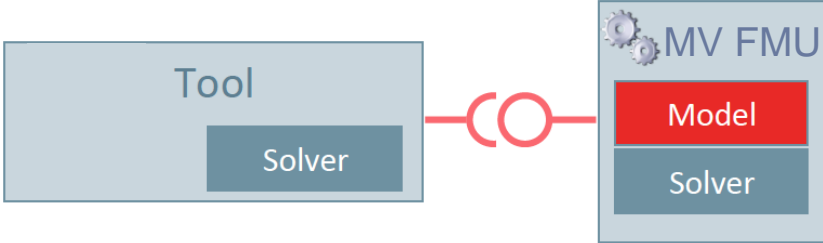
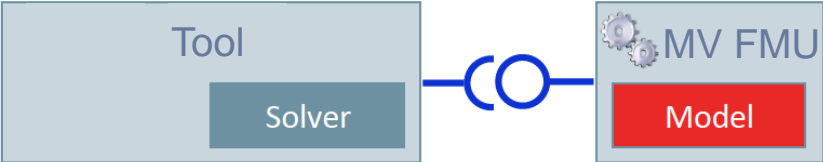
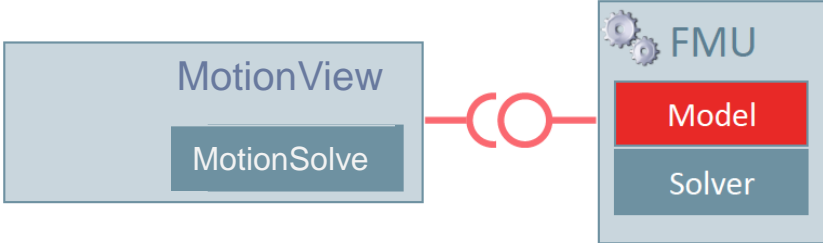


FMU SUPPORT

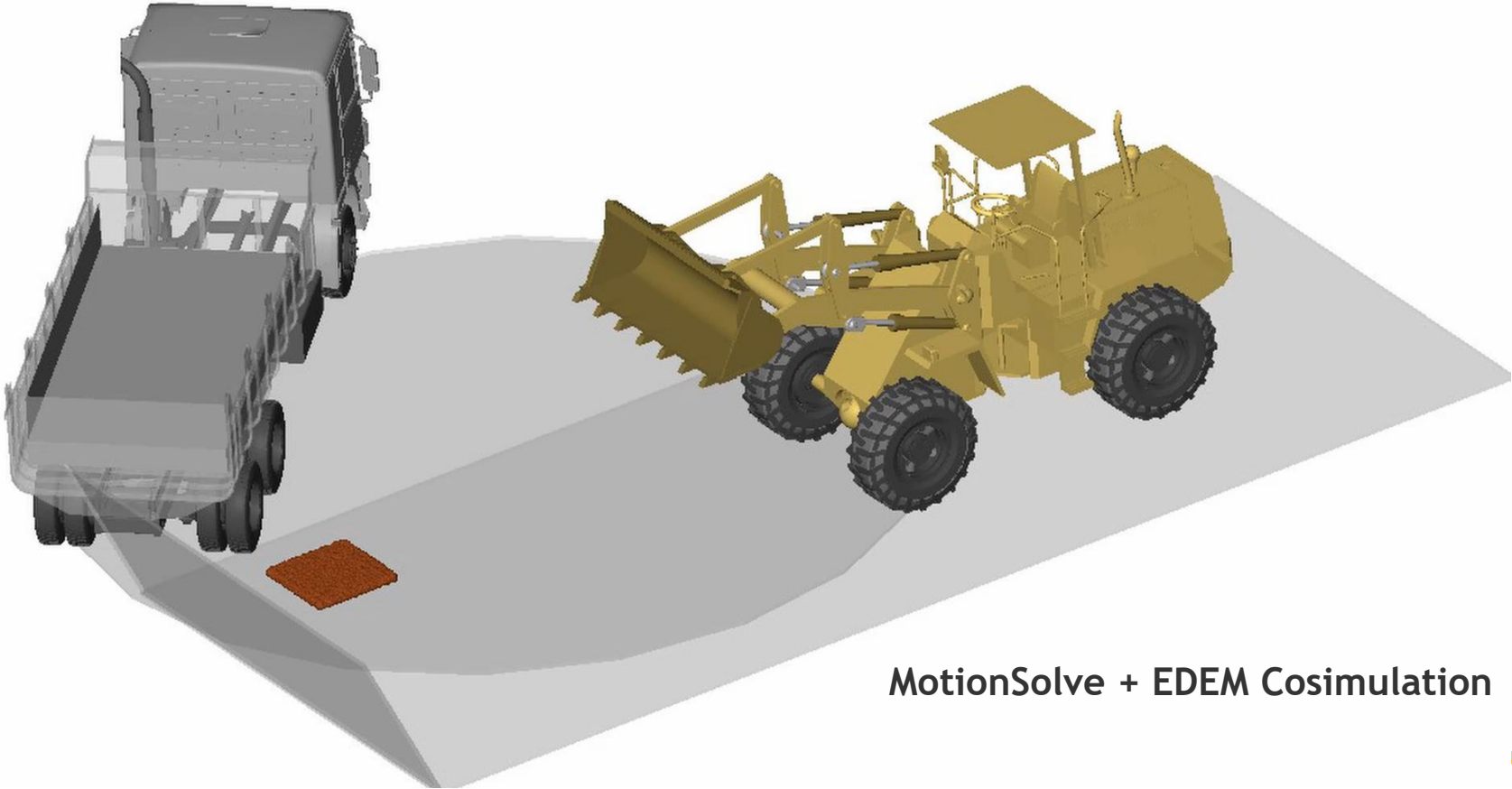
Model Exchange



Co-Simulation



DEM SIMULATIONS



MotionSolve + EDEM Cosimulation



CONCLUSION – THE ALTAIR MOTION SOLUTION...

01

A complete
solution for
analysts &
designers

02

Solve realistic,
multi-domain
problems

03

Exciting new
capabilities in
2019.0

04

Aggressive
development of
new capabilities

